1 Eigen Value (15 points)

Suppose $\lambda_1, \lambda_2, ..., \lambda_n$ are eigen values of matrix *A* Prove:

- $\lambda_1 + \lambda_2 + \ldots + \lambda_n = trace(A)$.
- $\lambda_1 \lambda_2 \dots \lambda_n = \det(A).$
- *AB* and *BA* have the same set of eigen values.
- A and A^T have the same set of eigen values.

2 Covariance & Expectation (15 points)

If we define cov(X, Y|Z) as below, prove the following equations.

cov(X, Y|Z) = E[(X - E[X|Z])(Y - E[Y|Z])|Z]

- Var(X) = Var(E[X|Y]) + E(Var[X|Y])
- cov(X, Y|Z) = E[XY|Z] E[X|Z]E[Y|Z]
- cov(X,Y) = E[cov(X,Y|Z)] + cov(E[X|Z],E[Y|Z])

3 Matrix Derivative (14 points)

•
$$\frac{\partial x^T A x}{\partial x} = 2x^T A$$

• $\frac{\partial trace(X^T A X)}{\partial X} = X^T (A + A^T)$

4 Random Variable (10 points)

Assume X as a random variable from uniform distribution U(0,1). Compute PDF for $\sqrt{X} \& X^2$.

5 Rank (8 points)

Prove that if P is a full rank matrix, matrices M and $P^{-1}MP$ have the same set of eigen values.

6 Matrix Factorization (14 points)

- Prove that every symmetric positive definite matrix A has a unique factorization of the form $A = LL^T$, where L is a lower triangular matrix with positive diagonal entries.
- Suppose *A* is a matrix and we have A = QR (*Q* is an orthonormal matrix). in this case, *SVD* of matrix *A* will be look like the *SVD* of matrix *R*; however, they will not be identical. Find the difference between these two *SVD* factorizations.

7 Nilpotent matrix (10 points)

square matrix such as N is a nilpotent matrix if we can find k, which is a positive integer, that fits in the equation below.

$$N^k=0$$

The smallest k that fits in this equation is called the index of N. prove that if A is a nilpotent matrix with index k, I - A is an invertible matrix then find its inversion.

8 MAP (14 points)

Suppose *X*, *Y* are independent normal random variables with mean μ and variance 1, where $\mu \sim Uni(0, 1)$.

$$f_{\mu}(t) = \begin{cases} 1 & t \in [0,1] \\ 0 & o.w \end{cases}$$

- Find the joint distribution of μ , *X*, *Y*. ($f_{\mu,X,Y}(t,x,y)$).
- Find the MAP estimate of μ .